```
1 * CG1 •
            Eric
            Eric
            ((Robodoc is driving around Eric))
2*
            (.)
           °ia°↓
3*PAT:
            ∘ves°↓
4 * CG1:
            prøv at se kan du huske vi talte om
            try to see can you remember we talked about that
            look do you remember we talked about that
5*
            Martin han ville komme der↑
           Martin he would come there↑
           Martin he would appear there↑
           °ja°↓ (.)
6*PAT:
            °ves°↓ (.)
            ((Robodoc stops facing Eric))
7*GP:
            godmorgen #1 Eric (.) eller goddag
            good morning Eric (.) or good day
            °qoddaq°
8*PAT:
            °good day°
9*GP:
            kan [du se mig
            can [you see me
10*CG1:
                [£kan du se #2 det er] Martin£
                [£can you see it's ] Martin£
11*PAT:
            jа
            yes
           £ja↑£
12*CG1:
            £yes\f
            (2.8)
13*
```



at.

Fig #1 CG1 looks at screen and leans slightly over to bodily align with Eric and share his perspective



Fig #2 CG1 looks leans over to look at Eric's face bodily selecting him as recipient